

Höger koordinat-system

$$\vec{F} = (F_x, F_y, F_z) = F_x \hat{e}_x + F_y \hat{e}_y + F_z \hat{e}_z$$

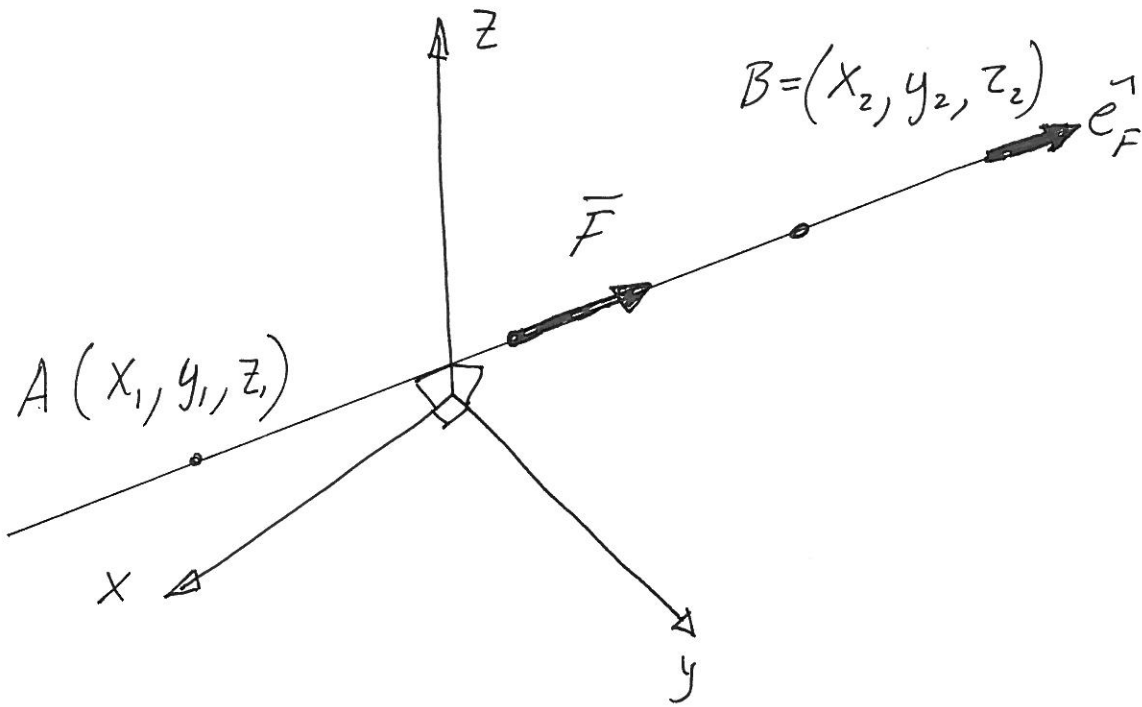
$$\vec{F} = (\vec{F}_x + \vec{F}_y + \vec{F}_z)$$

$\vec{F}_x, \vec{F}_y, \vec{F}_z =$ komponenter

$F_x, F_y, F_z =$ komponenter

$$F = |\vec{F}| = \sqrt{F_x^2 + F_y^2 + F_z^2}$$

$$\vec{F} = F \cos \theta_x \hat{e}_x + F \cos \theta_y \hat{e}_y + F \cos \theta_z \hat{e}_z$$

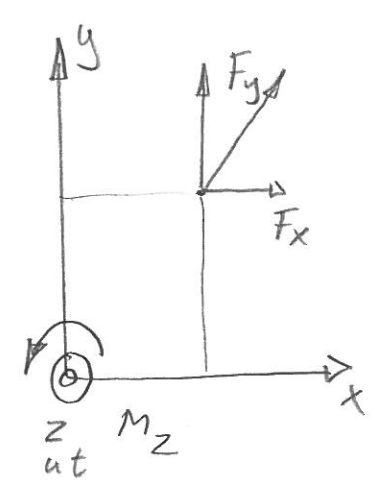
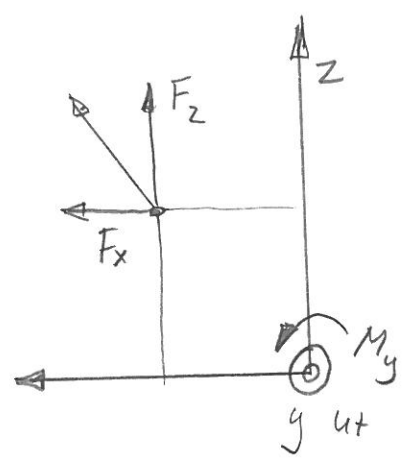
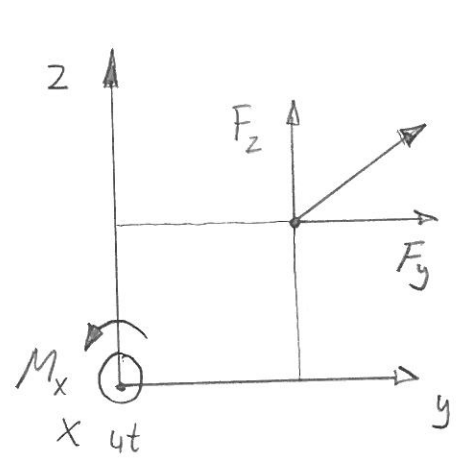
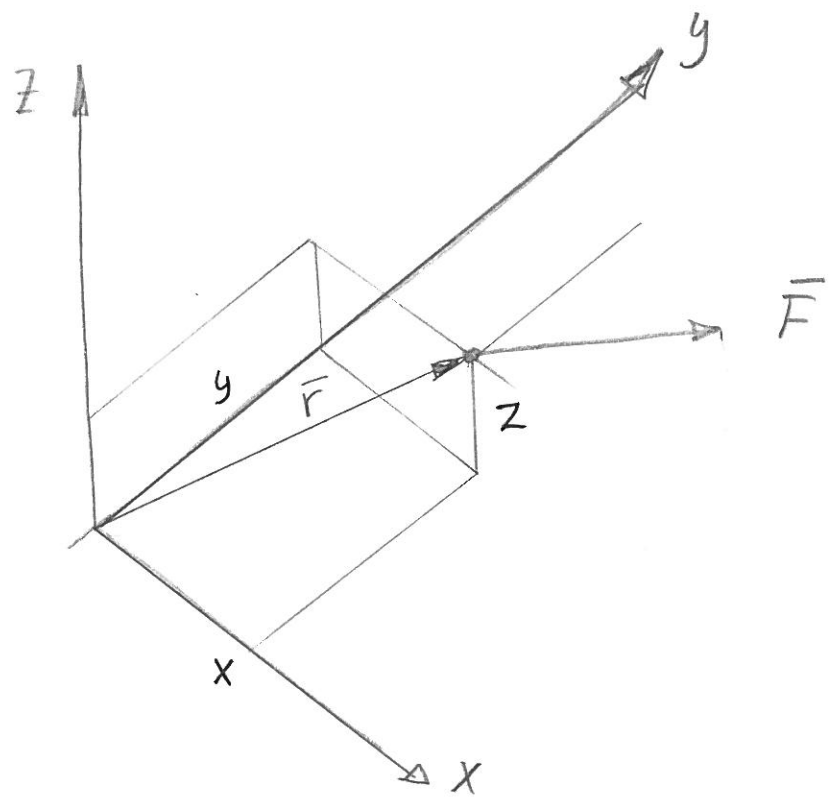


$$\vec{F} = F \cdot \vec{e}_F$$

$$\begin{aligned} \vec{AB} &= (x_2 - x_1) \vec{e}_x + (y_2 - y_1) \vec{e}_y + (z_2 - z_1) \vec{e}_z \\ &= ((x_2 - x_1), (y_2 - y_1), (z_2 - z_1)) \end{aligned}$$

$$|\vec{AB}| = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

$$\vec{e}_F = \frac{\vec{AB}}{|\vec{AB}|} = \frac{((x_2 - x_1), (y_2 - y_1), (z_2 - z_1))}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}}$$



$$M_x = F_z \cdot y - F_y \cdot z = y \cdot F_z - z \cdot F_y$$

$$M_y = F_x \cdot z - F_z \cdot x = z \cdot F_x - x \cdot F_z$$

$$M_z = F_y \cdot x - F_x \cdot y = x \cdot F_y - y \cdot F_x$$

$$\vec{M} = (M_x, M_y, M_z)$$

RÄKNEREGEL

$$\vec{A} \times \vec{B} = \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix} = \begin{vmatrix} \hat{e}_x & \hat{e}_y \\ A_x & A_y \\ B_x & B_y \end{vmatrix} - \begin{vmatrix} \hat{e}_x & \hat{e}_z \\ A_x & A_z \\ B_x & B_z \end{vmatrix} + \begin{vmatrix} \hat{e}_y & \hat{e}_z \\ A_y & A_z \\ B_y & B_z \end{vmatrix}$$

$$= (A_y \cdot B_z - B_y \cdot A_z) \hat{e}_x + (A_z \cdot B_x - B_z \cdot A_x) \hat{e}_y + (A_x \cdot B_y - B_x \cdot A_y) \hat{e}_z = -\vec{B} \times \vec{A}$$

Moment

$$\vec{M} = \vec{r} \times \vec{F}$$

↑
Lagevektor

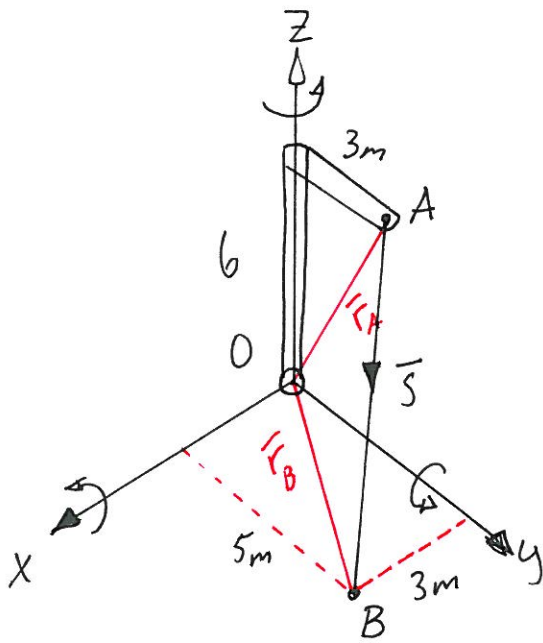
Kraftvektor

$$\vec{r} = (x, y, z)$$

$$\vec{F} = (F_x, F_y, F_z)$$

$$\vec{M} = \vec{r} \times \vec{F} = \begin{vmatrix} e_x & e_y & e_z \\ x & y & z \\ F_x & F_y & F_z \end{vmatrix} = \left((y \cdot F_z - z \cdot F_y), (z \cdot F_x - x \cdot F_z), (x \cdot F_y - y \cdot F_x) \right) \\ = \left((F_z \cdot y - F_y \cdot z), (F_x \cdot z - F_z \cdot x), (F_y \cdot x - F_x \cdot y) \right) \\ (M_x, M_y, M_z)$$

Ex

Stag AB spännkraft ^{6.}

1,4 kN.

a) Bestäm \vec{S} på A som vektor

$$\begin{aligned}\vec{r}_{AB} &= \vec{r}_B - \vec{r}_A = (3, 5, 0) - (0, 3, 6) \\ &= (3, 2, -6) \text{ m}\end{aligned}$$

Enhetsvektorn

$$\begin{aligned}\hat{e}_{AB} &= \frac{\vec{r}_{AB}}{|\vec{r}_{AB}|} = \frac{3, 2, -6}{\sqrt{3^2 + 2^2 + (-6)^2}} = \\ &= \frac{3, 2, -6}{\sqrt{9 + 4 + 36}} = \frac{(3, 2, -6)}{7}\end{aligned}$$

$$\vec{S} = S \cdot \hat{e}_{AB} = \frac{S(3, 2, -6)}{7} = \frac{1400}{7}(3, 2, -6)$$

$$\vec{S} = 200(3, 2, -6) \text{ N} = (600, 400, -1200) \text{ N}$$

b) Bestäm momentet mot origo

$$\vec{M}_o = \vec{r}_A \times \vec{S} = 200 \cdot \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ 0 & 3 & 6 \\ 3 & 2 & -6 \end{vmatrix} = \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ 0 & 3 & 6 \\ 600 & 400 & -1200 \end{vmatrix}$$

$$= 200(3 \cdot -6 - 6 \cdot 2, 6 \cdot 3 - 0 \cdot -6, 0 \cdot 2 - 3 \cdot 3)$$

$$= 200(-30, 18, -9) \text{ Nm} = (-6000, 3600, -1800) \text{ Nm}$$

6.